



CODESYS Feature Briefing, March 2024 Georg Seidel, Head of Application Technology



Override for Single Axis Movements



Outlook



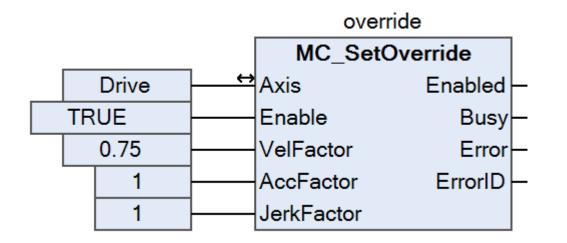
Override for Single Axis Movements



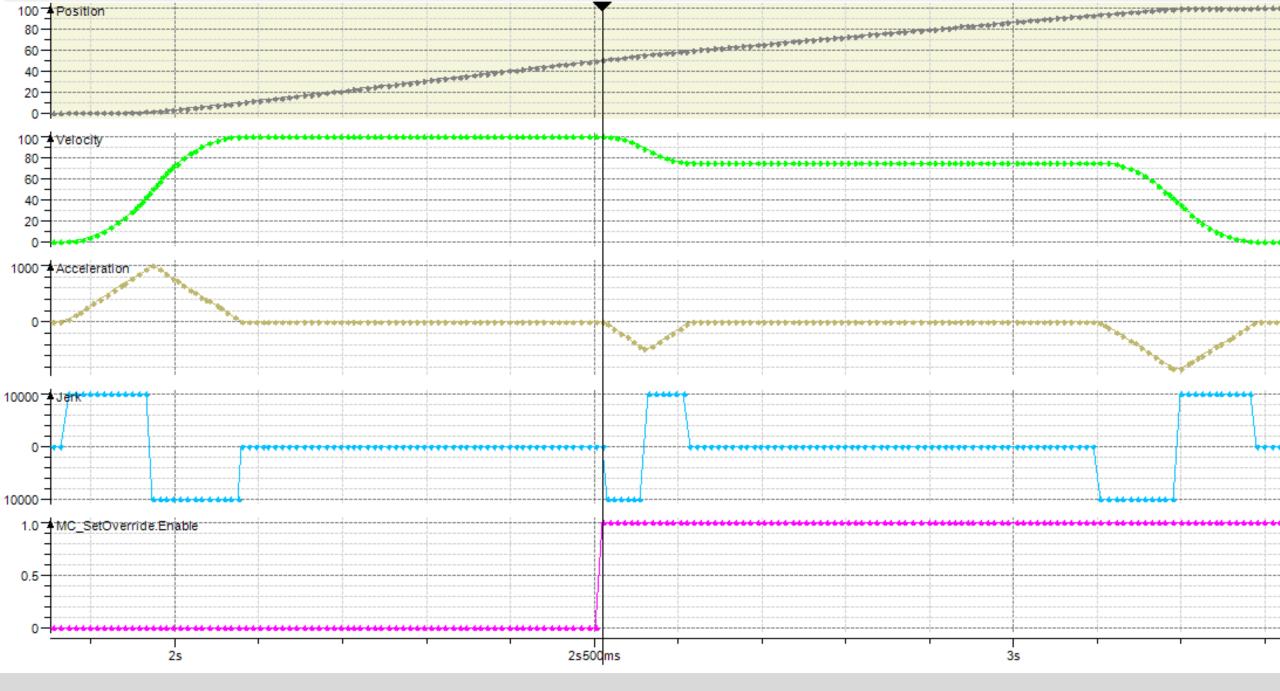
Outlook

Override for Single Axis Function Blocks (PLCopen MC Part 1)

Support for function block MC_SetOverride



Example: movement from position 0 to position 100 with override

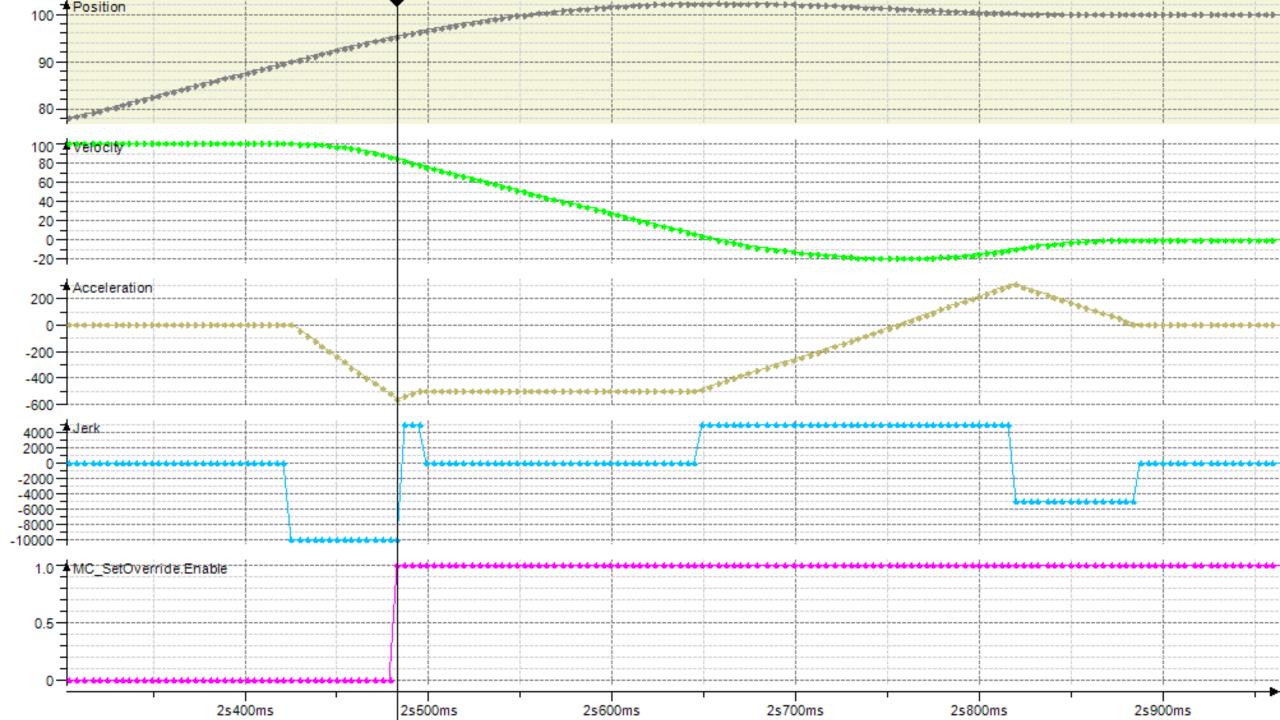


Applies to all single axis movements with a few exceptions

- MC_Stop is not affected.
- MC_PositionProfile, MC_VelocityProfile, and MC_AccelerationProfile are not affected. (Will be deprecated, MC_CamIn should be used.)
- Synchronized movements (MC_CamIn, MC_GearIn, MC_Phasing): Slave axes are only affected during ramping in.
- MC_GearInPos is not affected.

Caveats

- Velocity ramp types sin² and quadratic_smooth should not be used with MC_SetOverride. (Overshoot issues may occur.)
- Changing the acceleration and/or jerk override may lead to position overshoot
- Example: movement to position 100, acceleration and jerk override reduced to 50% while decelerating





Override for Single Axis Movements

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Outlook

Improvements of MC_CamIn

- Distance based ramping in (inputs MasterStartDistance and MasterSyncPosition)
- API for creating cam tables programmatically
- More cam segment types (polynomials of degree 7, inclined and modified sine segments)
- Tappets with sub-cycle timing accuracy



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